

TETRAHEDRON EQUATIONS, BOUNDARY STATES AND HIDDEN STRUCTURE OF $\mathcal{U}_q(D_n^{(1)})$

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ABSTRACT. Simple periodic $3d \rightarrow 2d$ compactification of the tetrahedron equations gives the Yang-Baxter equations for various evaluation representations of $\mathcal{U}_q(\widehat{sl}_n)$. In this paper we construct an example of fixed non-periodic $3d$ boundary conditions producing a set of Yang-Baxter equations for $\mathcal{U}_q(D_n^{(1)})$. These boundary conditions resemble a fusion in hidden direction.

The tetrahedron equation can be viewed as a local condition providing existence of an infinite series of Yang-Baxter equations. In the applications to quantum groups the method of tetrahedron equation is a powerful tool for generation of R -matrices and L -operators for various “higher spin” evaluation representations. This has been demonstrated in [1] for $\mathcal{U}_q(\widehat{sl}_n)$ and in [4] for super-algebras $\mathcal{U}_q(\widehat{gl}_{n|m})$.

The main principle producing the cyclic \widehat{sl}_n structure is the trace in hidden “third” direction. In this paper we introduce another boundary condition, a certain boundary states still providing the existence of effective Yang-Baxter equation and integrability.

We shall start with a short reminder of a (super-)tetrahedron equation and \widehat{sl}_n compactification in their elementary form. The simplest known tetrahedron equation in the tensor product of six spaces $B_1 \otimes F_2 \otimes \cdots \otimes F_5 \otimes B_6$ is

$$(1) \quad R_{B_1 F_2 F_3} R_{B_1 F_4 F_5} R_{F_2 F_4 B_6} R_{F_3 F_5 B_6} = R_{F_3 F_5 B_6} R_{F_2 F_4 B_6} R_{B_1 F_4 F_5} R_{B_1 F_2 F_3} ,$$

where $F_i = \{|0\rangle, |1\rangle\}_i$ is a representation space of Fermi oscillator

$$(2) \quad \mathbf{f}^+ |0\rangle = |1\rangle , \quad \mathbf{f}^- |1\rangle = |0\rangle .$$

Odd operators \mathbf{f}_i^\pm in different components i of their tensor product anti-commute and $(\mathbf{f}_i^\pm)^2 = 0$. It is convenient to introduce projectors

$$(3) \quad M_i = \mathbf{f}_i^+ \mathbf{f}_i^- , \quad M_i^0 = \mathbf{f}_i^- \mathbf{f}_i^+ , \quad [\mathbf{f}_i^+ , \mathbf{f}_i^-]_+ = M_i^0 + M_i = 1 .$$

Operator M_i^0 is the projector to vacuum, M_i is the occupation number and $M^0 M = 0$.

Space B_i stands for representation space of i -th copy of q -oscillator,

$$(4) \quad \mathbf{b}^+ \mathbf{b}^- = 1 - q^{2N} , \quad \mathbf{b}^- \mathbf{b}^+ = 1 - q^{2N+2} , \quad q^N \mathbf{b}^\pm = \mathbf{b}^\pm q^{N\pm 1} .$$

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In this paper we imply the unitary Fock space representation, $(\mathbf{b}^-)^\dagger = \mathbf{b}^+$, defined by

$$(5) \quad \mathcal{N}|n\rangle = |n\rangle n, \quad \mathbf{b}^-|0\rangle = 0, \quad |n\rangle = \frac{\mathbf{b}^{+n}}{\sqrt{(q^2; q^2)_n}} |0\rangle, \quad n \geq 0,$$

where $(x; q^2)_n = (1-x)(1-q^2x)\cdots(1-q^{2n-2}x)$. In terms of creation, annihilation and occupation number operators the R-matrices in (1) are given [4] by

$$(6) \quad R_{B_1 F_2 F_3} = M_2^0 M_3^0 - q^{N_1+1} M_2 M_3^0 + q^{N_1} M_2^0 M_3 - M_2 M_3 + \mathbf{b}_1^- \mathbf{f}_2^+ \mathbf{f}_3^- - \mathbf{b}_1^+ \mathbf{f}_2^- \mathbf{f}_3^+$$

and

$$(7) \quad R_{F_1 F_2 B_3} = M_1^0 M_2^0 + M_1 M_2^0 q^{N_1+1} - M_1^0 M_2 q^{N_1} - M_2 M_3 + \mathbf{f}_1^+ \mathbf{f}_2^- \mathbf{b}_3^- - \mathbf{f}_1^- \mathbf{f}_2^+ \mathbf{b}_3^+.$$

Both operators R are unitary roots of unity. The constant tetrahedron equation (1) can be verified in the operator language straightforwardly.

Define next the “monodromy” of R-matrices as the ordered product

$$(8) \quad R_{\Delta_n(B_1 F_2), F_3} = R_{B_{1:1} F_{2:1} F_3} R_{B_{1:2} F_{2:2} F_3} \cdots R_{B_{1:n} F_{2:n} F_3} \stackrel{\sim}{=} \prod_{j=1..n} R_{B_{1:j} F_{2:j} F_3}.$$

Here the convenient “co-product” notation stands for a tensor power of corresponding spaces,

$$(9) \quad \Delta_n(B_1) = \bigotimes_{j=1}^n B_{1:j}, \quad \Delta_n(F_2) = \bigotimes_{j=1}^n F_{2:j}.$$

The repeated use of (1) provides

$$(10) \quad R_{\Delta_n(B_1 F_2), F_3} R_{\Delta_n(B_1 F_4), F_5} R_{\Delta_n(F_2 F_4), B_6} R_{F_3 F_5 B_6} \\ = R_{F_3 F_5 B_6} R_{\Delta_n(F_2 F_4), B_6} R_{\Delta_n(B_1 F_4), F_5} R_{\Delta_n(B_1 F_2), F_3}.$$

Note the conservation laws:

$$(11) \quad v^{-M_3} u^{-M_5} \left(\frac{u}{v}\right)^{N_6} R_{F_3 F_5 B_6} = R_{F_3 F_5 B_6} v^{-M_3} u^{-M_5} \left(\frac{u}{v}\right)^{N_6}.$$

Multiplying (10) by the u, v -term in $F_3 \otimes F_5 \otimes B_6$ and by $R_{F_3 F_5 B_6}^{-1}$, and making then the traces over $F_3 \otimes F_5 \otimes B_6$, we come to the Yang-Baxter equation

$$(12) \quad L_{\Delta_n(B_1 F_2)}(v) L_{\Delta_n(B_1 F_4)}(u) R_{\Delta_n(F_2 F_4)}(u/v) = R_{\Delta_n(F_2 F_4)}(u/v) L_{\Delta_n(B_1 F_4)}(u) L_{\Delta_n(B_1 F_2)}(v),$$

where

$$(13) \quad L_{\Delta_n(B_1 F_2)}(v) = \text{Str}_{F_3} (v^{-M_3} R_{\Delta_n(B_1 F_2), F_3}), \quad R_{\Delta_n(F_2 F_4)}(w) = \text{Tr}_{B_6} (w^{N_6} R_{\Delta_n(F_2 F_4), B_6}).$$

This is the case of $\mathcal{U}_q(\widehat{sl}_n)$. Two-dimensional R-matrices (13) have the centers

$$(14) \quad J_i = \sum_{j=1}^n M_{i:j} \quad \text{for fermions and} \quad J_1 = \sum_{j=1}^n N_{1:j} \quad \text{for bosons.}$$

Irreducible components of R -matrices and L -operators (13) correspond to fixed values of J_i . In particular, $\Delta_n(F)$ is the sum of all antisymmetric tensor representations of sl_n ,

$$(15) \quad \dim \Delta_n(F) = 2^n = \sum_{k=0}^n \frac{n!}{k!(n-k)!}.$$

The Dirac spinor representation of D_n has the same dimension 2^n , it is the direct sum of two irreducible Weyl spinors with dimensions 2^{n-1} . It is evident intuitively, the structure of D_n will appear if the total occupation number J of $\Delta_n(F)$ is not a center of L -operators and R -matrices, but all operators preserve just the parity of J . Also, since the dimension of vector representation of D_n is $2n$, we need to double the number of bosons.

Consider now two copies of (1) and further of (10) glued in the “second” direction. This consideration keeps the desired space $\Delta_n(F)$ and doubles the number of bosons. The repeated use of (1) provides

$$(16) \quad \begin{aligned} & R_{\Delta(B_1)F_2\Delta(F_3)} R_{\Delta(B_1)F_4\Delta(F_5)} R_{F_2F_3B_6} R_{\Delta'(F_3F_5)B_6} \\ &= R_{\Delta'(F_3F_5)B_6} R_{F_2F_3B_6} R_{\Delta(B_1)F_4\Delta(F_5)} R_{\Delta(B_1)F_2\Delta(F_3)}, \end{aligned}$$

where

$$(17) \quad R_{\Delta(B_1)F_2\Delta(F_3)} = R_{B_1F_2F_3} R_{B_1'F_2F_3'} \quad \text{and} \quad R_{\Delta'(F_3F_5)B_6} = R_{F_3'F_5'B_6} R_{F_3F_5B_6}.$$

The key observation is the existence of a family of eigenvectors of operator $R_{\Delta'(F_3F_5)B_6}$:

$$(18) \quad R_{\Delta'(F_3F_5)B_6} |\psi_{\Delta(F_3)}(v) \psi_{\Delta(F_5)}(u) \psi_{B_6}(u/v)\rangle = |\psi_{\Delta(F_3)}(v) \psi_{\Delta(F_5)}(u) \psi_{B_6}(u/v)\rangle,$$

where

$$(19) \quad \Delta(F) = F' \otimes F, \quad |\psi_{\Delta(F)}(v)\rangle = (1 + v^{-1} \mathbf{f}^{+'} \mathbf{f}^+) |0\rangle,$$

and in the unitary basis (3)

$$(20) \quad \langle 2k+1 | \psi_B(w) \rangle = 0, \quad \langle 2k | \psi_B(w) \rangle = w^k \sqrt{\frac{(q^{4k+4}; q^4)_\infty}{(q^{4k+2}; q^4)_\infty}}.$$

The normalization of ψ_B is given by

$$(21) \quad \langle \bar{\psi}_B(w) | (\mathbf{b}^\pm)^{2m} | \psi_B(w) \rangle = w^m \frac{(q^{2+4m} w^2; q^4)_\infty}{(w^2; q^4)_\infty}.$$

Considering now a length- n chain of (16) in the “third” direction and applying vectors $\psi_{\Delta(F_3)}(u)$, $\psi_{\Delta(F_5)}(v)$ and $\psi_B(u/v)$, we come to the Yang-Baxter equation

$$(22) \quad \begin{aligned} & L_{\Delta_n(\Delta(B_1)F_2)}(v) L_{\Delta_n(\Delta(B_1)F_4)}(u) R_{\Delta_n(F_2F_4)}(u/v) \\ &= R_{\Delta_n(F_2F_4)}(u/v) L_{\Delta_n(\Delta(B_1)F_4)}(u) L_{\Delta_n(\Delta(B_1)F_2)}(v) \end{aligned}$$

without trace construction:

$$(23) \quad L_{\Delta_n(\Delta(B_1)F_2)}(v) = \langle \bar{\psi}_{\Delta(F_3)}(v) | R_{\Delta_n(\Delta(B_1)F_2), \Delta(F_3)} | \psi_{\Delta(F_3)}(v) \rangle$$

and

$$(24) \quad R_{\Delta_n(F_2 F_4)}(w) = \langle \bar{\psi}_{B_6}(w) | R_{\Delta_n(F_2 F_4), B_6} | \psi_{B_6}(w) \rangle .$$

Matrix elements of $R_{\Delta_n(F_2 F_4)}(w)$ can be calculated with the help of (21) and similar identities. The invariants of L -operator (23) and R -matrix (24) are: the parity of $J_2 = \sum \mathcal{M}_{2:j}$, similar parity of J_4 and

$$(25) \quad J_1 = \sum_{j=1}^n (\mathcal{N}_{1:j} - \mathcal{N}'_{1:j}) .$$

A choice of different spectral parameters in bra- and ket-vectors in (23,24) is equivalent to the choice of equal spectral parameters by means of a gauge transformation.

The structure of D_n representation ring can be verified explicitly by a direct calculation of matrix elements of R -matrix (24) for small n and check of factor powers of $\det(\lambda - R)$.

As to $2n$ -bosons space, irreducible components of $\Delta_n(\Delta(B_1))$ are in general infinite dimensional. However, a choice of Fock and anti-Fock space representations, $\text{Spectrum}(\mathcal{N}_{1:j}) = 0, 1, 2, \dots$ and $\text{Spectrum}(\mathcal{N}'_{1:j}) = -1, -2, -3, \dots$, makes $\Delta_n(\Delta(B_1))$ a direct sum of symmetric tensors of $O(2n)$.

The main result of this paper is a step forward to a classification of *integrable boundary conditions* in three-dimensional models. At least two scenarios are hitherto known: quasi-periodic boundary condition (13) and the boundary states condition (23,24). These conditions can be imposed for a layer-to-layer transfer matrix in different directions independently. In both scenarios the spectral parameters of effective two-dimensional models reside the boundary. Also, the boundary admits twists making the quantum groups classification inapplicable [3]. It worth noting one more possible scenario of integrable boundary conditions: yet unknown $3d$ reflection operators satisfying the tetrahedron reflection equations [2].

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